

# Setting up Ubuntu Laptops and the Duckietops

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**This is the guide to install the Duckietop laptops (Thinkpad 450s) for the class from scratch. You can follow this guide to set up your own Ubuntu laptop as well.**

## Install Ubuntu

Get Ubuntu 14.04 (64-bit) bootable image on USB.

Reboot computer and hit “enter”.

hit F12

Choose *Install Ubuntu*

Connect to a network by double clicking on the network.

Choose all the standard settings.

### **Official course laptops only:**

For the main user, use: name/password ubuntu/quackquack.

For the hostname: choose duckietop1, duckietop2, etc.

Ubuntu installs.

## Install most things using the duckietop\_setup.sh script

We have a setup script that does most things for you.

Download the setup script:

```
$ wget https://raw.githubusercontent.com/duckietown/Software/master/setup/duckietop_setup.sh
```

Run it using:

```
$ source duckietop_setup.sh
```

## Install extra packages

```
sudo apt-get install openssh-server byobu vim avahi-discover avahi-utils ecryptfs-utils htop  
git-extras
```

## Install dropbox

Follow instructions here: <https://www.dropbox.com/install?os=lnx>

**Official course laptops only:** Install dropbox with the account [duckietop@gmail.com](mailto:duckietop@gmail.com).

## Install Google Chrome

You probably need [Google Chrome](#), otherwise ctrl+c in Google Docs doesn't work in firefox

## Install ROS (included in the script)

This is the minimal sequence of commands:

```
sudo sh -c 'echo "deb http://packages.ros.org/ros/ubuntu $(lsb_release -sc) main" >  
/etc/apt/sources.list.d/ros-latest.list'  
sudo apt-key adv --keyserver hkp://pool.sks-keyservers.net --recv-key 0xB01FA116  
sudo apt-get update  
sudo apt-get install ros-indigo-desktop-full
```

## (optional) Install redshift

This is Flux for Linux. It is an accessibility/lab safety issue: bright screens damage eyes.

Install redshift and run it.

```
sudo apt-get install redshift-gtk
```

Set to "autostart" from the icon.

## (Optional) Install insync

Install insync using the account [duckietop@gmail.com](mailto:duckietop@gmail.com)

Follow instructions at:

<https://www.insynchq.com/>

## (Optional) Remove notifications

Notifications are distracting. Use the instructions at <http://askubuntu.com/a/464697> to disable notifications.

## (Optional) Add passwordless sudo for ubuntu and test users mack and jack

Run the command:

```
sudo visudo
```

Then add the following lines, one for each user:

```
sudo apt-get install git-extras
```

```
ubuntu ALL=(ALL) NOPASSWD: ALL
```

```
mack ALL=(ALL) NOPASSWD: ALL
```

```
jack ALL=(ALL) NOPASSWD: ALL
```

Things to add and test:

---

## Install ROS and Git and Checkout Duckietown Software repo

```
laptop $ git clone git@github.com:duckietown/Software.git
duckietown
```

## Install additional required dependencies using install scripts in the repo

```
laptop $ cd ~/duckietown
laptop $ source duckietown_install_car.sh
laptop $ source duckietown_install_laptop.sh
```

This will install all the necessary dependencies and some tools.

## Set up ROS environment

Now we are ready to make the workspace. First you need to source the baseline ROS indigo environment:

```
laptop $ source /opt/ros/indigo/setup.bash
```

Then, build the workspace (you have to be under the `catkin_ws` folder to invoke `catkin_make`) e.g. `nano ~/.bashrc`)

```
laptop $ catkin_make
```

Now, let's setup ROS environment in your ~/.bashrc.

Open the ~/.bashrc file in your editor of choice (Make sure that the following lines are in your ~/.bashrc file and if not, add them at the end of the file:

```
laptop $ source ~/duckietown/environment.sh
laptop $ source ~/duckietown/set_ros_master.sh
laptop $ export ROSLAUNCH_SSH_UNKNOWN=1
```

This means that by default your laptop will set itself as the ROS\_MASTER.

Remember to "source the bashrc file for the change to take effect. Do

```
laptop $ source ~/.bashrc
```

Note that bashrc is (only) sourced every time you open a new terminal. For the change to take effect at old terminals, you must run the source command.

Check that everything is ok by writing:

```
laptop $ echo $ROS_MASTER_URI
> http://duckietop1.local:11311/
```

Reboot by

```
laptop $ sudo reboot
```

At this point your duckietop / ubuntu laptop is ready for action.

Exit